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INVESTIGATION OF VERTICAL FORCED VIBRATION IN THE LONGITUDINAL - VERTICAL PLANE OF A BINDER THAT SOFTENS THE CRUSH BETWEEN COTTON ROWS

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Abstract: The forces acting on the bobbin due to moisture, density, and hardness of the tangle formed between rows of cotton were studied. Roll on in the longitudinal - vertical plane, in addition to the forward motion, the aggregate of the blade performs a forced oscillating motion in the vertical direction. Forced vibration motion of the roller in the vertical direction was studied. It was found that the force was linearly dependent on the amount and speed of the deformation of the coil under the influence of rolling. The sum of the forces arising from the variation of the physico-mechanical properties of the concrete was found.[1] It can be seen from the analysis that, for the given working conditions, the quality of the smoothing of the roller by the roller was achieved due to its total mass, that is, the parallelogram mechanism and the joint mass, the uniformity of the pressure spring, and the correct choice of the angle of deviation from the horizon during the operation of the parallelogram mechanism's longitudinal pullers.[2]

Keywords: friction, moisture, density, rolling, softening of friction, rolling stock, oscillatory motion, differential equation, parallelogram, hinge, deformation, static, coefficient

Introduction. It is known that in the conditions of Bukhara region, it is possible to save the newly sprouted cotton seedlings by softening the slush that occurs due to rainfall after the germination of cotton, by working between the rows. By loosening the thicket, favorable conditions are created for the growth of cotton, it is possible to reduce the escape of moisture from the soil, improve the air exchange in the soil, improve the assimilation of nutrients and reduce the chances of cotton disease.[3-4]

Forces N_z acting on the reel N_x are constantly changing. Because of this, there is no reeling in the work process in the longitudinal - vertical plane, in addition to the forward motion, a forced vibration movement in the vertical direction is performed by the aggregate. Based on this, we will study the forced vibration motion of the roller in the vertical direction. For this purpose, we construct the differential equation of vertical oscillations of the coil using the computational scheme presented in Fig. 1 . It will have the following appearance [3 - 4; p. 24]

$$m \frac{d^2 Z}{dt^2} = mg + Q_n - N_z (1 + \mu t g \alpha), \quad (1)$$

where Z is the vertical coordinate axis passed through movable hinges I and L of the parallelogram mechanism, m ;

t – time, s.

in the expression (1.2) as the sum of the forces N_z that are linearly dependent on the amount and speed of the deformation of the fabric under the influence of rolling N_d , N_v

and which arise from the variation of the physical and mechanical properties of the fabric N_t [5-6; p. 91], i.e

$$N_z = N_d + N_v + N_t. \quad (2)$$

Taking this into account, the expression (1.1) will have the following form

$$m \frac{d^2 Z}{dt^2} = mg + Q_n - (N_d + N_v + N_t)(1 + \mu t g \alpha). \quad (3)$$

When the coil is in static equilibrium

$$N_d = h_t C_t B; \quad (4)$$

$$N_v = 0; \quad (5)$$

$$N_v = 0; \quad (6)$$

$$Q_n = Q_0, \quad (7)$$

in this h_t - the depth of immersion of the roller in the state of equilibrium, m;

in this C_t - the density of the coil, which is brought to the width of one unit covering the roller, Ns/m^2 .

Q_0 - the tension force when the parallelogram mechanism touches the pressure spring in the initial state, i.e., in the static equilibrium state of the roller, N .

Galtakmola from the state of static equilibrium Z to the distance down when moved

$$N_d = h_t C_t B; \quad (8)$$

$$N_v = Z b_t B; \quad (9)$$

$$N_v = -\Delta N_t; \quad (10)$$

$$Q_n = Q_0 - C_p Z, \quad (11)$$

in this b_t - the resistance coefficient of the coil per unit width of the coil, Ns/m^2 .

N_d , N_v , N_z and Q_n ni (8) - We put the values of expressions (9) into (3):

$$m \frac{d^2 Z}{dt^2} = mg + Q_0 - C_p Z - [(h_t C_t B + Z b_t B + -\Delta N_t)](1 + \mu t g \alpha). \quad (12)$$

When the coil is in static equilibrium

$$mg + Q_0 - h_t C_t B(1 + \mu t g \alpha) = 0. \quad (13)$$

Taking this into account, equation (8) becomes:

$$m \frac{d^2 Z}{dt^2} = -C_p Z - (C_t Z B + b_t Z B)(1 + \mu t g \alpha) + \Delta N_t (1 + \mu t g \alpha) \quad (14)$$

$$m \frac{d^2Z}{dt^2} + b_t B \frac{dZ}{dt} (1 + \mu t g \alpha) + [C_p + C_t B (1 + \mu t g \alpha)] Z = \Delta N_t (1 + \mu t g \alpha). \quad (15)$$

To solve this expression, ΔN_t we assume that the power changes according to the harmonic law during the work process [5-6; p. 81].

$$\Delta N_t = \sum_{n=1}^{n_1} \Delta N^n \cos \omega t, \quad (16)$$

in this ΔN^n – the amplitude of alternating ΔN , power harmonics, N;

$n = 1, 2, \dots, n_1$ – number of harmonics;

n_1 – the last harmonic to be taken into account;

$\omega = \Delta N^n$ rotational frequency of power change, s^{-1} .

(16) into account, (17) has the following form

$$m \frac{d^2Z}{dt^2} + b_t B \frac{dZ}{dt} (1 + \mu t g \alpha) + [C_p + C_t B (1 + \mu t g \alpha)] Z = \left(\sum_{n=1}^{n_1} \Delta N^n \cos \omega t \right) (1 + \mu t g \alpha). \quad (18)$$

$$\frac{d^2Z}{dt^2} + \frac{b_t B}{m} \frac{dZ}{dt} (1 + \mu t g \alpha) + \frac{[C_p + C_t B (1 + \mu t g \alpha)]}{m} Z = \frac{1}{m} \left(\sum_{n=1}^{n_1} \Delta N^n \cos \omega t \right) (1 + \mu t g \alpha). \quad (19)$$

This equation represents a non-homogeneous second-order differential equation, and its solution representing forced vertical oscillations of the coil has the following form [7-8; p. 54-55].

$$Z(t) = \frac{\sum_{n=1}^{n_1} [\Delta N^n \cos(n\omega t - \varepsilon)] (1 + \mu t g \alpha)}{\sqrt{\left[\frac{c_p + c_t B (1 + \mu t g \alpha)}{m} - (n\omega)^2 \right]^2 + \left[\frac{b_t B (1 + \mu t g \alpha)}{m} \right]^2} (n\omega)^2} \quad (20)$$

$$\text{in this } \varepsilon = \arctg \frac{b_t B (1 + \mu t g \alpha) (n\omega)^2}{c_p + c_t B (1 + \mu t g \alpha) - m (n\omega)^2}.$$

According to this expression, the amplitude of forced vertical oscillations of the coil is equal to:

$$A = \frac{\frac{1}{m} \sum_{n=1}^{n_1} \Delta N^n (1 + \mu t g \alpha)}{\sqrt{\left[\frac{c_p + c_t B (1 + \mu t g \alpha)}{m} - (n \omega)^2 \right]^2 + \left[\frac{b_t B (1 + \mu t g \alpha)}{m} \right]^2} (n \omega)^2}, \quad (21)$$

From the analysis of expressions (10) and (11), it can be seen that for the given working conditions, the quality of the smoothing of the roller by the roller is achieved due to its total mass, that is, the mass of the parallelogram mechanism and the gradil, the uniformity of the pressure spring, the correct choice of the angle of deviation from the horizon during the operation of the parallelogram mechanism's longitudinal pulls. [9-10-11-12]

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CONTENTS

PRIMARY PROCESSING OF COTTON, TEXTILE AND LIGHT INDUSTRY

Korabayev Sh.	3
From street traffic to space: innovations in autonomous vehicles	
Egamov N.	10
Investigation of vertical forced vibration in the longitudinal - vertical plane of a binder that softens the crush between cotton rows	
Khamraeva S., Kadirova D., Davlatov B.	15
Determination of alternative technological factors for the production of functional fabric with a complex structure	
Khamraeva S., Kadirova D., Daminov A.	21
Designing fabrics for a given stretchability	
Kuliyev T., Rozmetov R., Tuychiev T., Sharipov Kh.	28
The effect of the angle of heat agent supply to the drying - cleaning equipment on cotton quality and cleaning efficiency of the equipment	
Abdujabbarov M., Alieva D., Karimov R.	35
Determination of the influence of the length of the tested yarn samples on their mechanical characteristics	
Jurayeva M., Nabidjonova N.	41
Research on physical and mechanical properties of fabric selected for special clothing of preschool children	
Yangiboev R., Allakulov B., Gulmirzayeva S.	45
Studying the alternative technological factors of the loom in the production of textiles based on basalt yarn	
Ganikhanov Kh., Mavlyanov A., Abdusamatov A., Mirzaumidov A.	55
Analysis of the main technological parameters of the condenser	
Mavlyanov A., Mirzaumidov A.	60
The scientific basis of the lightened shaft	
Elmanov A., Mirzaumidov A.	69
Modeling of laser processing of thin-walled steel gears	
Nurillaeva Kh., Mirzaumidov A.	77
Cotton cleaner with multifaceted grates	
Ganikhanov Kh., Mavlyanov A., Abdusamatov A., Mirzaumidov A.	83
The equation of motion of cotton fiber in the condenser	
Khuramova Kh., Xoshimxojaev M.	89
Progressive method of cotton regeneration	

Abdukarimova M., Lutfullaev R., Usmanova N., Mahsudov Sh.

Evaluation of aestheticity of women's dress models based on deep learning models

94

**GROWING, STORAGE, PROCESSING AND AGRICULTURAL
PRODUCTS AND FOOD TECHNOLOGIES**

Zufarov O., Isroilova Sh., Yulchiev A., Serkayev K.

101

Theoretical aspects of obtaining oxidation-stable vegetable oils

Toshboyeva S., Dadamirzaev M.

110

Filling sauces for canned fish and their layer kinetics

Atamirzaeva S., Saribaeva D., Kayumova A.

115

Prospects for the use of rose hips in food technology

Turgunpolatova Sh.

121

Study of the quality of fruit pastela products

Sultanov S.

Analysis of experiments on the process of deodorization of vegetable oil using 126
floating nozzles

Adashev B.

132

Physical-chemical analysis of oil taken from seeds of safflower

Ismailov M.

137

Influence of surface layer thickness on hydraulic resistance of the device

Khurmamatov A., Boyturayev S., Shomansurov F.

142

Detailed analysis of the physicochemical characteristics of distillate fractions

Madaminova Z., Khamdamov A., Xudayberdiyev A.

Preparing peach seed for oil extraction and improving oil extraction through 154
pressing

Aripova K.

162

Methods of concentration of fruit juices and their analysis

Djuraev Kh., Urinov Sh.

Theoretical and experimental study of the crack formation device in the shell of 168
apricot kernels

CHEMICAL TECHNOLOGIES

Urinboeva M., Abdikamalova A., Ergashev O., Eshmetov I., Ismadiyarov A.

175

Study of the composition and main characteristics of petroleum oils and their
emulsions

Tursunqulov J., Kutlimurotova N.

Application of 1-(2-hydroxy-1-naphtoazo)-2-naphthol-4-sulfo acid in 182
amperometric determination of scandium ion

Kucharov A.

191

Development of coal enrichment and gas extraction technology for the use of construction materials industrial enterprises

Abdulkhaev T., Mukhammadjonov M., Mirzarakhimova F.

Isotherm of benzene adsorption and differential heat of adsorption on AgZSM-5 zeolite **198**

Vladimir L., Eshbaeva U., M.Ergashev

Innovative environmental packaging for separating storage of two components, allowing to extend the lifetime without preservatives **204**

Kodirov O., Ergashev O.

Energetics of adsorption of water molecules to aerosol **212**

Yusupov K., Erkabaev F., Ergashev D., Rakhimov U., Numonov M.

Synthesis of melamine-formaldehyde resins modified with n-butanol **219**

Ergashev O., Abdikamalova A., Bakhronov Kh., Askarova D., Xudoyberdiyev N., Mekhmonkhonov M., Xolikov K.

Thermodynamics of Congo red dye adsorption processes on mineral and carbon adsorbents **228**

Ergashev O., Maximov I.

Water vapor adsorption isotherm in zeolites regenerated by microwave thermoxidation method **235**

Jumaeva D., Zaripbaev K., Maximov I.

The elements and oxide content of the chemical composition of the feldspar **242**

MECHANICS AND ENGINEERING

Khudoyberdiev U., Izzatillaev J.

Analysis of research on small wind energy devices **249**

Atajonova S.

Mathematical model of system analysis of technological processes in the form of key principles for effective decision-making **258**

Kuchkarbayev R.

Mathematical modeling of heat transfer through single-layer and multi-layer cylindrical walls in buildings and structures **264**

Atambaev D.

Difference in the length of individual yarn composition of twisted mixed yarn and comparative analysis of single-thread elongation deformations **269**

Abdullayev S.

Modeling the functionalities of an automated system for managing movement in the air **276**

Turakulov A.

Describing computational domains in applications for solving three-dimensional problems of technological processes **285**

Mamaxonov A.

Mathematical model of machine aggregate of tillage equipment process	293
Khudayberdiyev A.	304
Technical and economic aspects of processing pyrolysis distillate into motor fuel	
Abdurahmonov J.	311
Research results on the selection of the mesh surface of a lint-cleaning device	
Vohidov M.	
Development of a program for determining eccentricity by analyzing the magnetic field in the air gap of an asynchronous motor	319
Utaev S., Turaev A.	
Analysis of methods and prospects for application of optical methods for control of working surfaces of cylinder liners of internal combustion engines	327
Boltabayev B.	
Determination of seed damage in the pneumatic transport system by conducting experiments	335
Azizov Sh., Usmanov O.	
Simulation of equation of motion of the new construction gin machine	339
Sharibaev N., Homidov K.	
Theoretical analysis of the coefficient of friction induced by the pressure force of a vertical rope acting from above and below	347
Aliyev B., Shamshidinov M.	
Improvement of the linter machine and development of its working scheme	356
Mukhametshina E.	
Analysis of cotton flow behavior in different pneumatic pipes	362
Yangiboev R., Allakulov B.	
Obtaining and analyzing correlational mathematical models of the sizing process	369
Mirzakarimov M.	
Efficient separation of fibers from saw teeth in the newly designed gin machine	379
Azambayev M.	
Measures to improve the quality of fluff	387
Abdullayev R.	
Scientific innovative development of cotton gining	392
Kholmirzaev F.	
Air flow control factors in pneumatic transport device	397
Sharibaev N., Makhmudov A.	
Separation of cotton from airflow in pneumatic transport systems of the cotton industry	404
Sharibaev N., Mirzabaev B.	

Effect of steam temperature on yarn moisture regulation in textile industry **410**

Sultanov S., Salomova M., Mamatkulov O. **415**

Increasing the useful surface of the mesh surface

Muhammedova M. **421**

Kinematics of the foot in a healthy person's foot and ankle injury

ADVANCED PEDAGOGICAL TECHNOLOGIES IN EDUCATION

Abdullayev H. **429**

Algorithm for creating structured diagrams of automatic control systems

Kodirov D., Ikromjonova N. **437**

On delayed technological objects and their characteristics

Uzokov F. **444**

Graphing circles, parabolas, and hyperbolas using second-order linear equations in excel

ECONOMICAL SCIENCES

Zulfikarova D. **449**

Issues of developing women's entrepreneurship

Ergashev U., Djurabaev O. **455**

Methods for assessing the effectiveness of waste recycling business activities in the environmental sector
